

1. Synopsis

What are we doing ?

- full 3D modelling of an NSTX Vertical Displacement Event (VDE)
- assessment of halo/wall currents and wall forces
- investigation of key physics and dynamics of these disruptions

Why ?

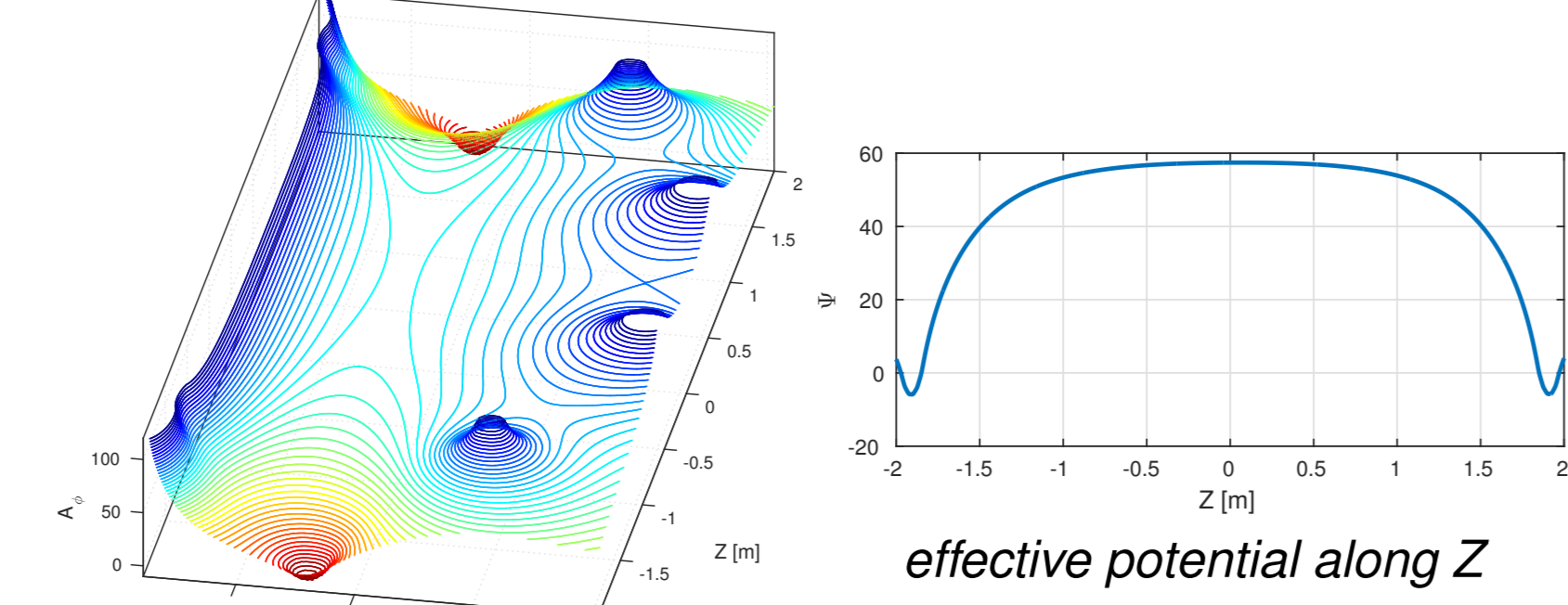
- forces during VDEs lead to **structural damage** to Plasma Facing Components (PFC)
- worst case VDE on ITER can result in machine shut-down

How ?

- numerical simulations using extended MHD code M3D-C1
 - finite-thickness axisymmetric resistive wall as a part of the computational domain
 - anisotropic** unstructured mesh providing C1 weak solution on 48 planes
 - cubic spline in toroidal direction for 3D effects
 - implicit** time-stepping

2. Phenomenology of VDEs

VDEs are inherent to diverted tokamak plasmas



external potential from PF coils

- diverted plasma sit on a saddle due to external field (PF coils) \Rightarrow elongation, **vertically unstable**
- conducting structures do not allow fast flux changes \Rightarrow **passive stabilisation** + feedback control
- loss of vertical control leads to deleterious contact with wall
 - transfer/induction of current from core \rightarrow halo \rightarrow wall \Rightarrow **forces and stresses**
 - scraping-off of $q_{edge} < 2 \Rightarrow$ 3D instabilities (kink), toroidal peaking of forces
 - thermal collapse, impurities \Rightarrow breaking of flux surfaces, runaway electrons

Experimental traces serve as modelling targets

- drift phase [Pfefferlé, 2017] $t_D \sim (L_w/R_w)(I_p/I_d)(Z_d/Z_w)^2 \sim 30\text{ms}$
 - slow** process (relaxation)
 - plasma mostly in force balance
 - advection (\approx rigid body), inductive coupling with wall \Rightarrow **implicit scheme**
- current quench $t_{CQ} \gtrsim L_p^*/R_p^* \sim 3\text{ms}$ [Wesley, 2006]
 - current transfer from plasma to wall
 - scrape-off of flux (advection-diffusion)
 - time-evolving** resistivity via thermal quench
- normal wall currents $\Delta t_H \sim t_{CQ}$ [Myers, 2017]
 - shared/induced currents in resistive halo
 - counter- I_p rotation $\Omega R \sim 3\text{km/s} = 0.1c_s$ for max 4 turns

VDE dynamics seem to be controlled by

- wall resistivity and external PF potential
- density and temperature of open field-line region
- breaking of flux-surfaces (3D instabilities) and heat conductivity
- viscosity, diffusivity and other transport coefficients (to lesser extent)

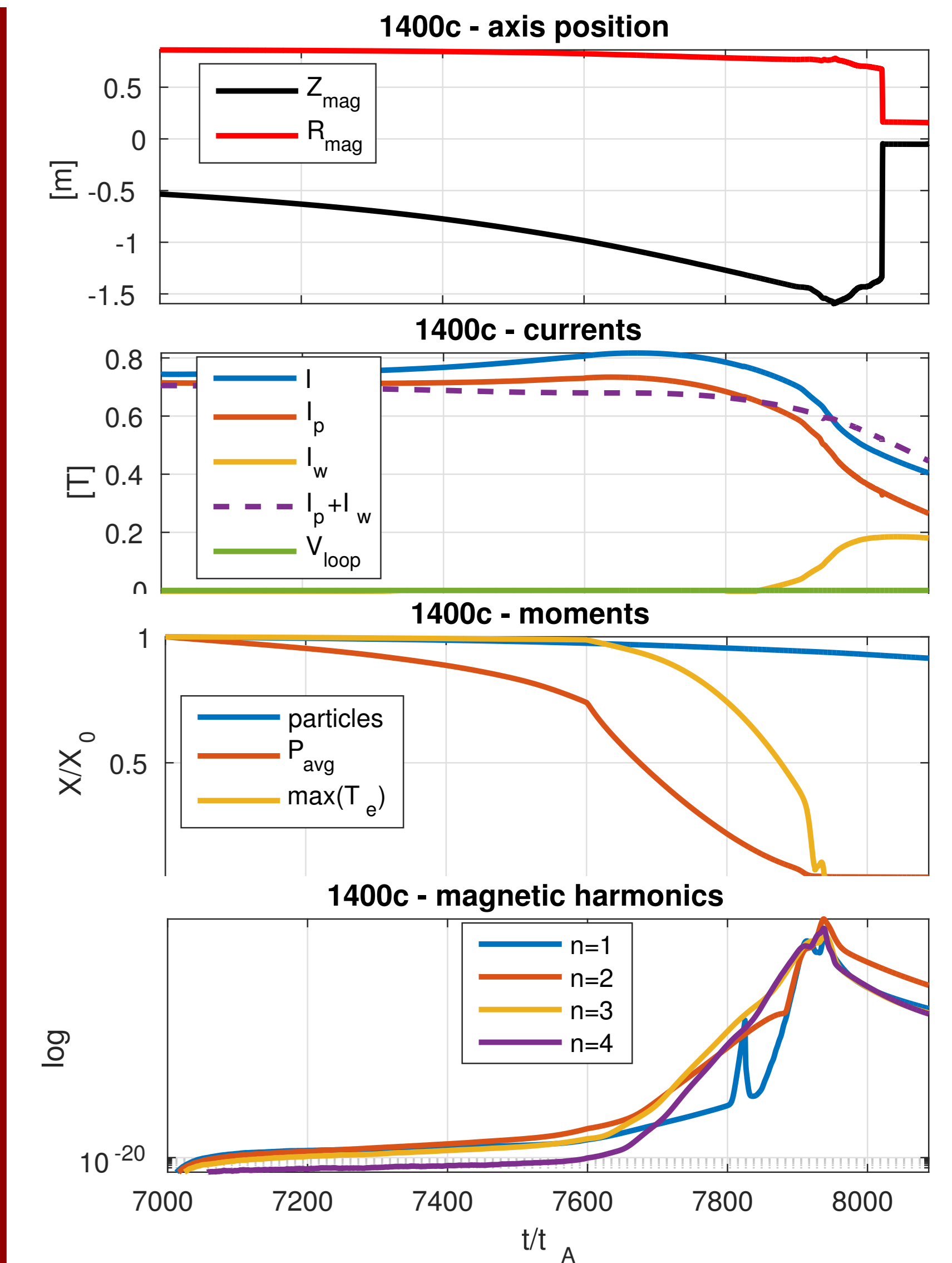
3. Numerical simulation of hot VDEs

Strategy

- perform **2D nonlinear** M3D-C1 simulations (90% of physical time) until plasma reaches wall
- linear stability analysis is performed along the way to monitor unstable modes
- expensive 3D nonlinear** simulations are deployed immediately when linear growth rates of instabilities (external kink) overcome $n = 0$ drift

Nonlinear 3D runs reveal complex dynamics (see figures on the right)

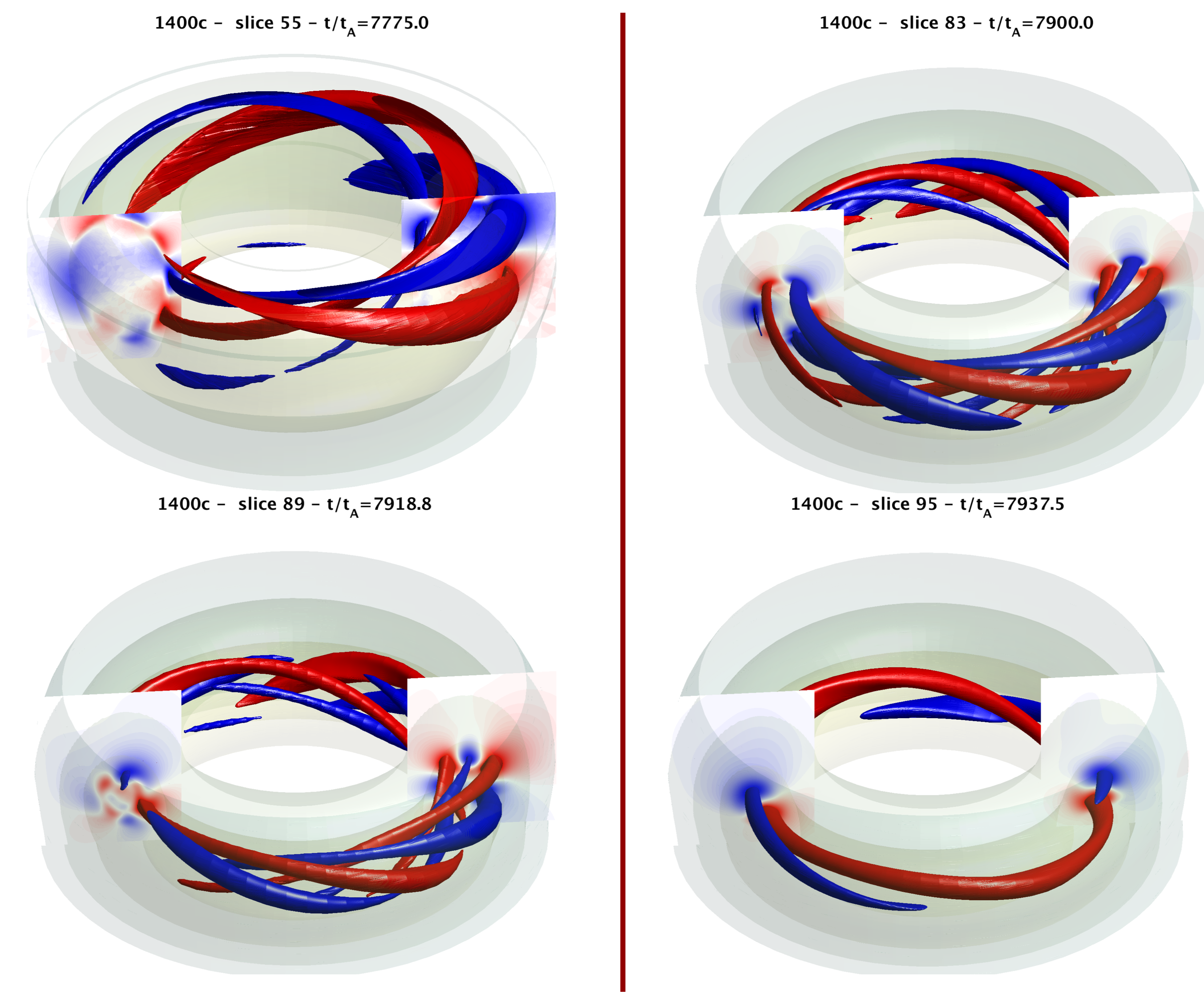
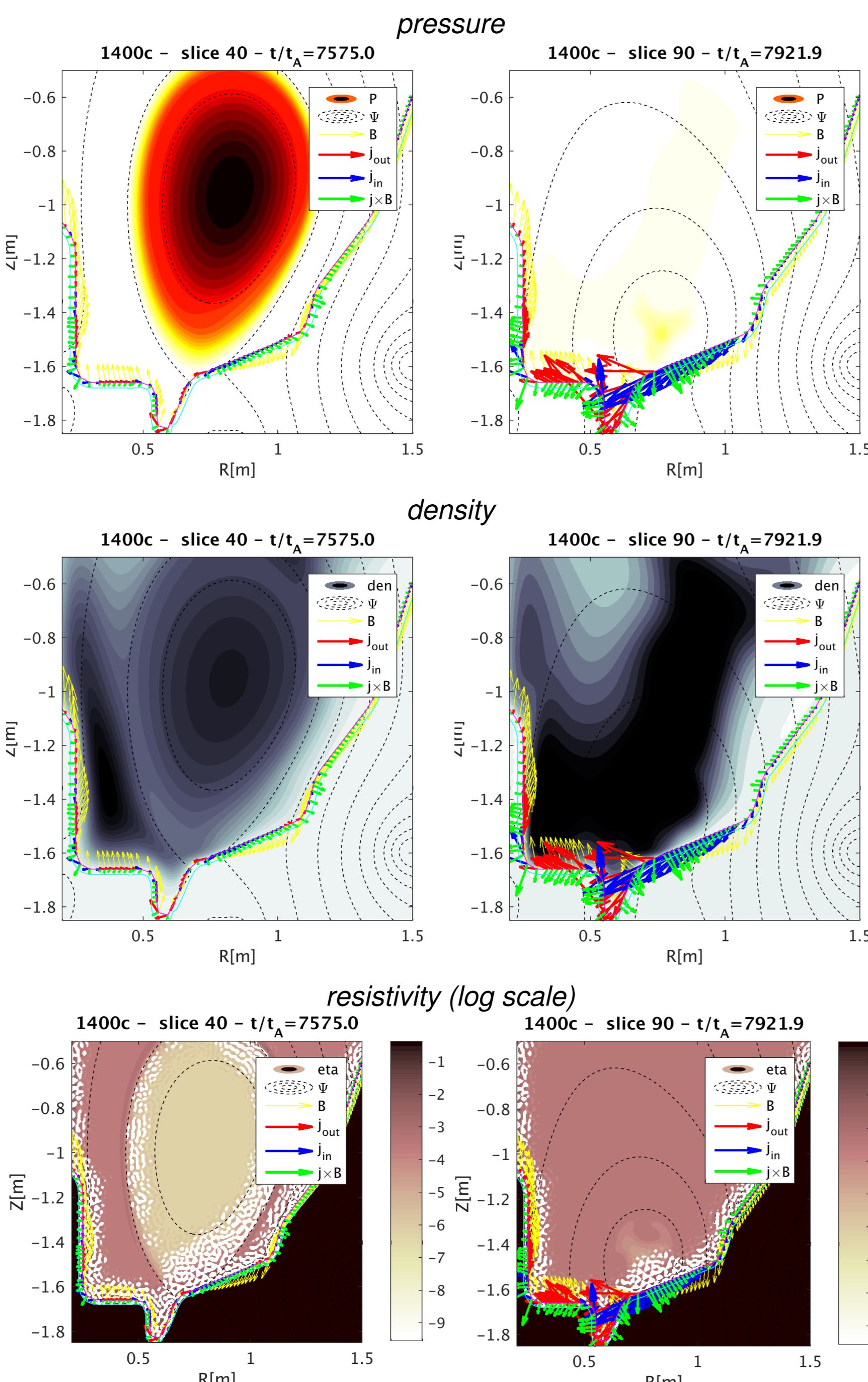
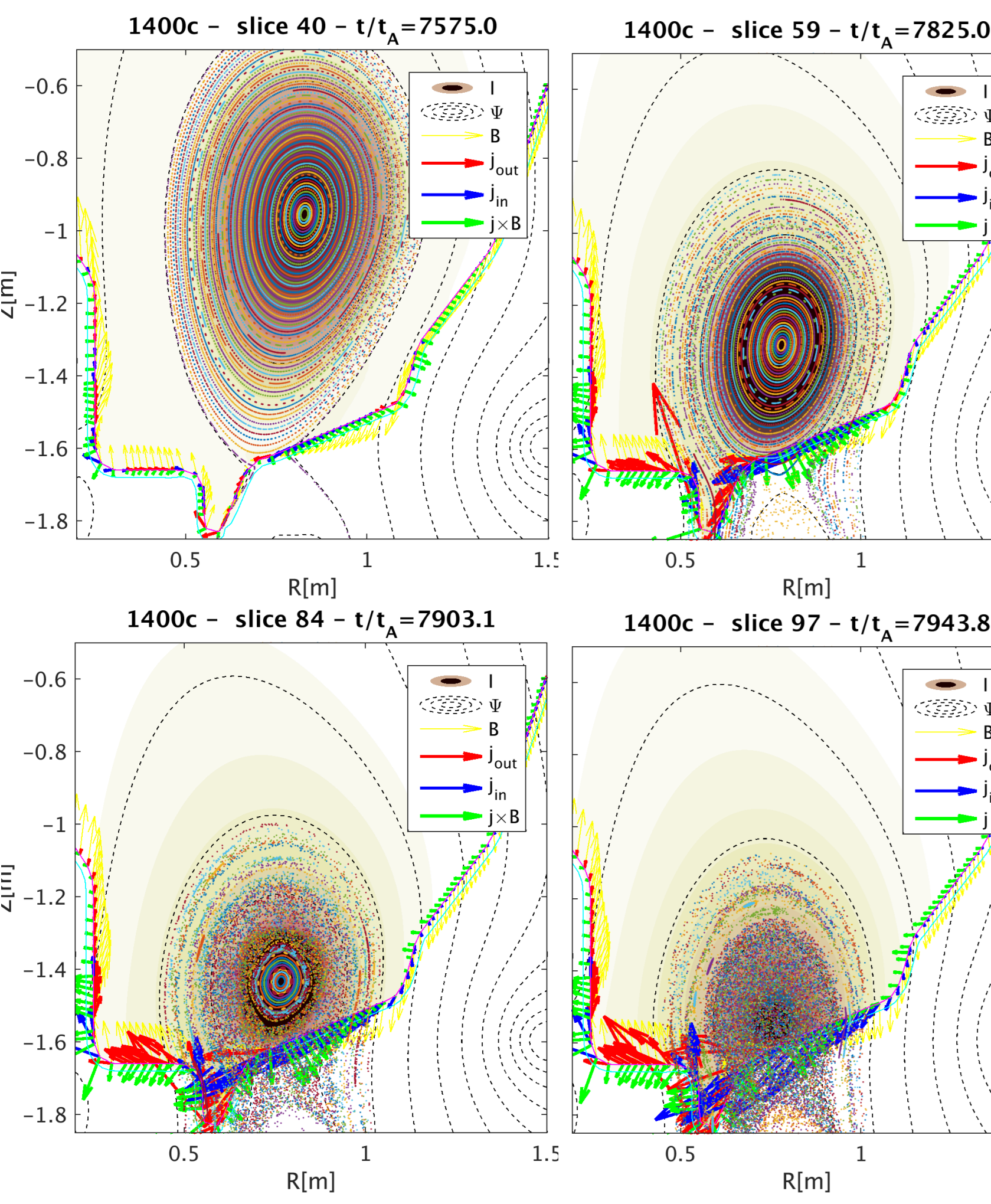
- Harmless drifting of plasma (in 3D)
- Vertical motion stalls via induced $n = 0$ wall currents
 - scrape-off of LCFS but $q_e > 2$ stable
 - thermal quench initiated by wetting with cold wall
- edge surface currents develop as $q_e < 2$
 - stabilise external kink
- rapid growth of all m, n modes
 - edge modes penetrate and merge into massive 1, 1
 - violent termination as $q_e < 1$
- current decays in residual cold plasma and resistive wall



4. Analysis and visualisation

Current quench induces halo/wall currents and provokes $j \times B$ forces

- peeling of flux leads to penetration of edge modes and **stochastisation** of field-lines \Rightarrow **thermal quench**

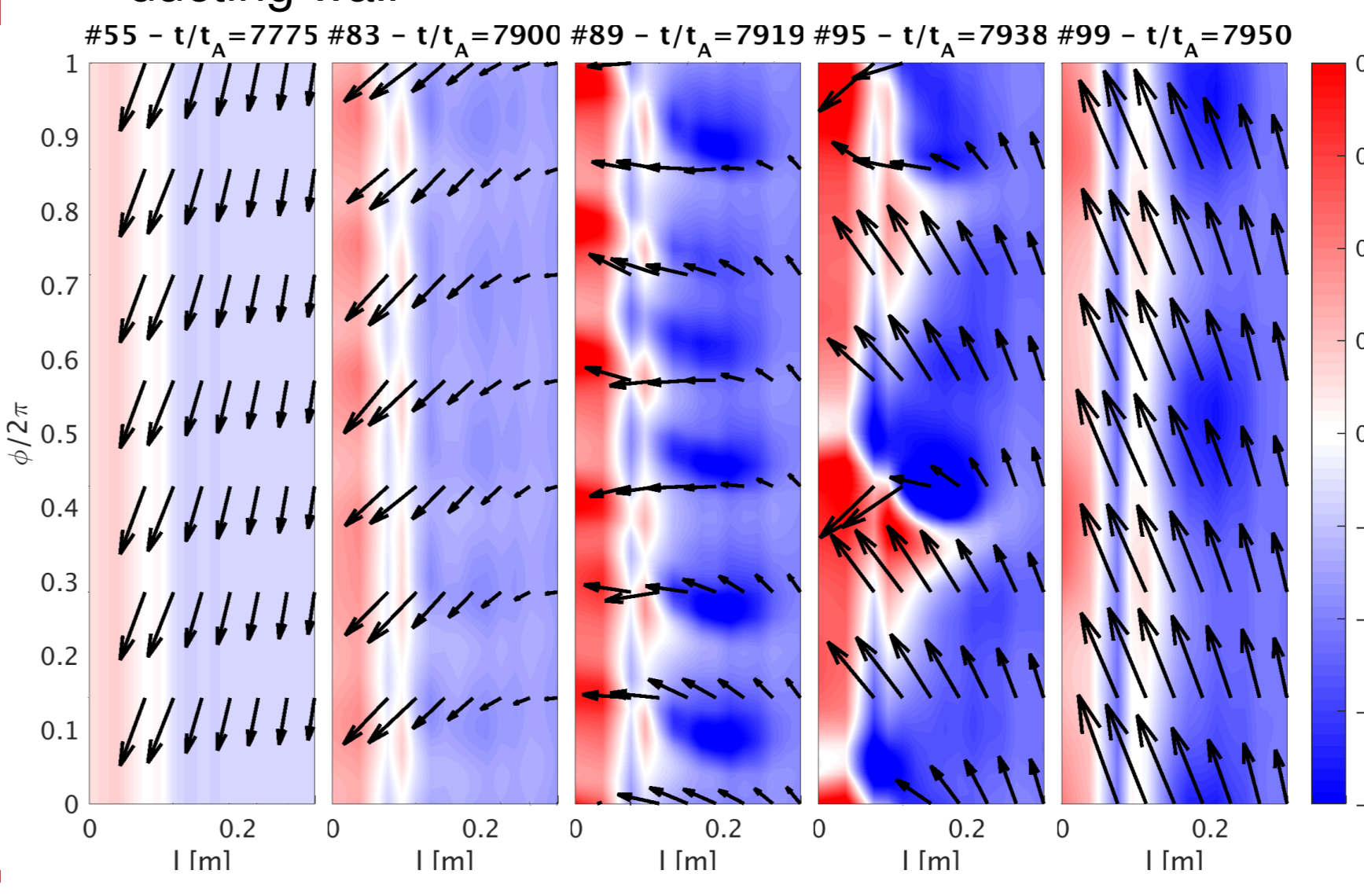


Non-axisymmetric modes form islands and current sheets near edge (see left figures)

- high- m and high- n mode numbers are **dominant** as $q_e > 1 - 2$ (but all modes are important)
- plasma shrinks and edge modes penetrate \Rightarrow core temperature ruined
- islands merge to lower m, n mode numbers
- no toroidal rotation but **shearing** of structures caused by q -values sweep

Current on divertor plate show time-evolving non-axisymmetric patterns

- Eddy currents** present to oppose vertical motion
- contact line defined by in and out currents (blue/red)
- transition period where **high-n structures** develop
- most intense halo currents with **low-n signature**
- wall current flows **co- I_p** as plasma shrinks into conducting wall



5. Concluding remarks

Summary

- M3D-C1 is employed to model NSTX VDEs with realistic parameters
 - anisotropic** mesh to resolve sharp gradients at plasma/wall contact point
 - implicit** scheme to resolve advection-diffusion stiff problem
- massive 3D nonlinear runs for evolution/saturation of non-axisymmetric structures
 - predominance of **edge high-n modes** in early stages of wall contact
 - cascade to **low-n** core modes as plasma disappears into wall
 - stochastisation** of field-lines causing rapid cooling of plasma
- virtual diagnostics of normal wall currents qualitatively agree with experimental data

Extensions and additional effects

- non-uniform / non-axisymmetric wall resistivity
- toroidal rotation, torque, plasma/wall boundary conditions, sheath physics

References

- D. Pfefferlé, to be submitted (2017).
- J. Wesley and al., GA-A25410 (2006).
- C. Myers, to be submitted (2017).